

Monitoring the stability of height network in Tallinn using Sentinel-1 data

Tõnis Oja
Anti Gruno
Contact:
tonis.oja@datel.ee

DATEL

 SILLE

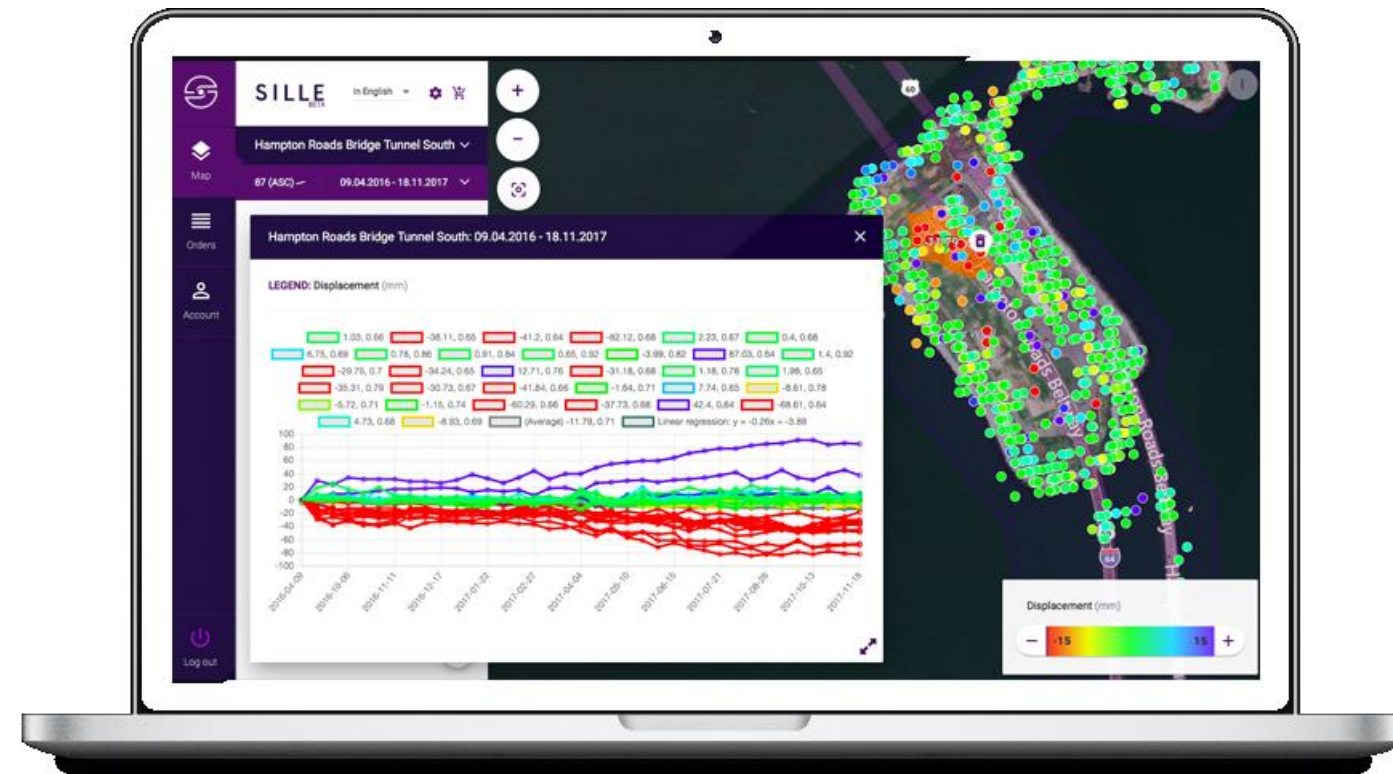
 esa

Nordic Geodetic Commission
General Assembly: Planet Ocean and Geodesy
Copenhagen, September 5-8, 2022

www.datel.eu
www.sille.space

● Hazards, changes, processes and damage can be identified and monitored:

- Infrastructure in urban areas
- Buildings, dams
- Mining, landslides
- Ports, airports
- Tunnels, railways
- Power-/pipelines
- Groundwater/oil extraction
- ...



- Satellite-based monitoring service:
 - Combines databases (clients, data, results), analysis tools (sarproz, GMT), map interface (MapServer), ...
 - Method: multitemporal SAR interferometry (InSAR)
 - Data: ESA Sentinel-1 C-SAR images
 - IW Mode, spatial and temporal resolution: 5x20 m, 6/12-day cycle

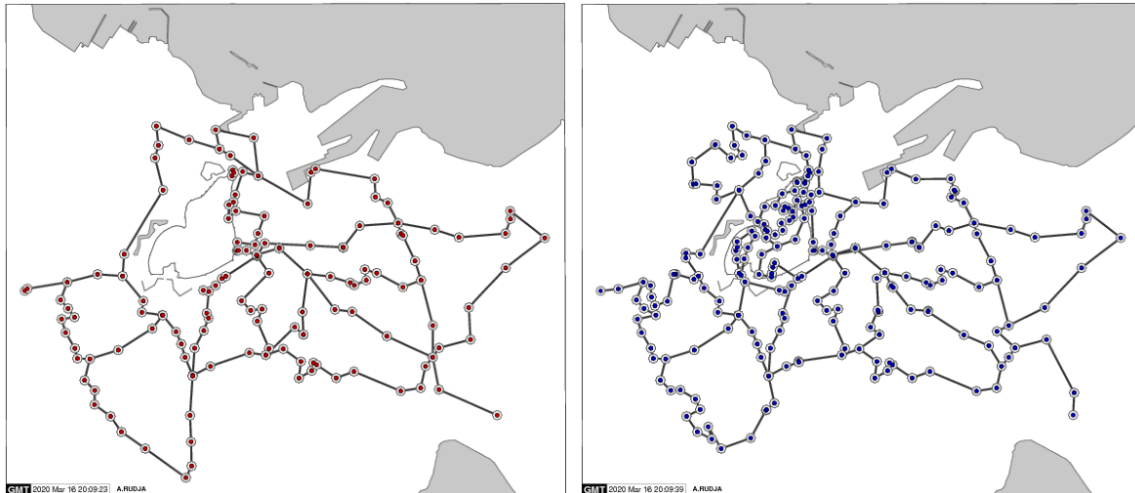
The following table contains a summary of useful orbital information for Sentinel-1A and –1B:

Altitude	Inclination	Period	Cycle	Ref. tube deviation	Local Time at Descending Node
693 km	98.18 deg	98.6 min	12 days	+ - 100 m	18:00 hours



SENTINEL-1 C-SAR instrument
sentinel.esa.int

- The aim of InSAR analysis was to monitor the stability of benchmarks (BMs) in Tallinn city center
 - Repeated levellings of 116 BMs
 - Uncertainty of heights: $u(H_{lev}) = 0.23-0.31$ mm
 - Uncertainty of velocities: $u(v_{lev}) = 0.03$ mm/y

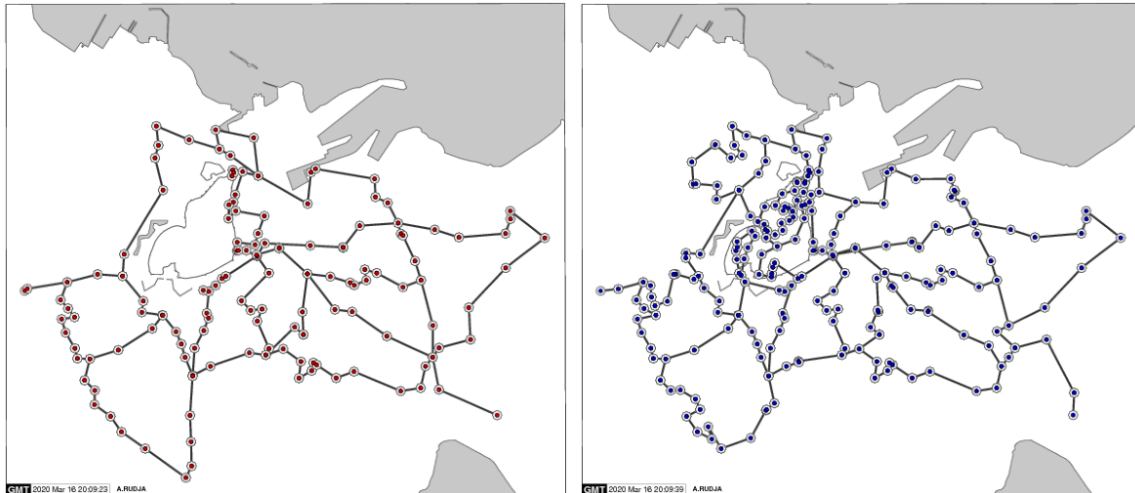


Precise leveling campaigns of the Tallinn height network undertaken in 2007/2008 and 2019

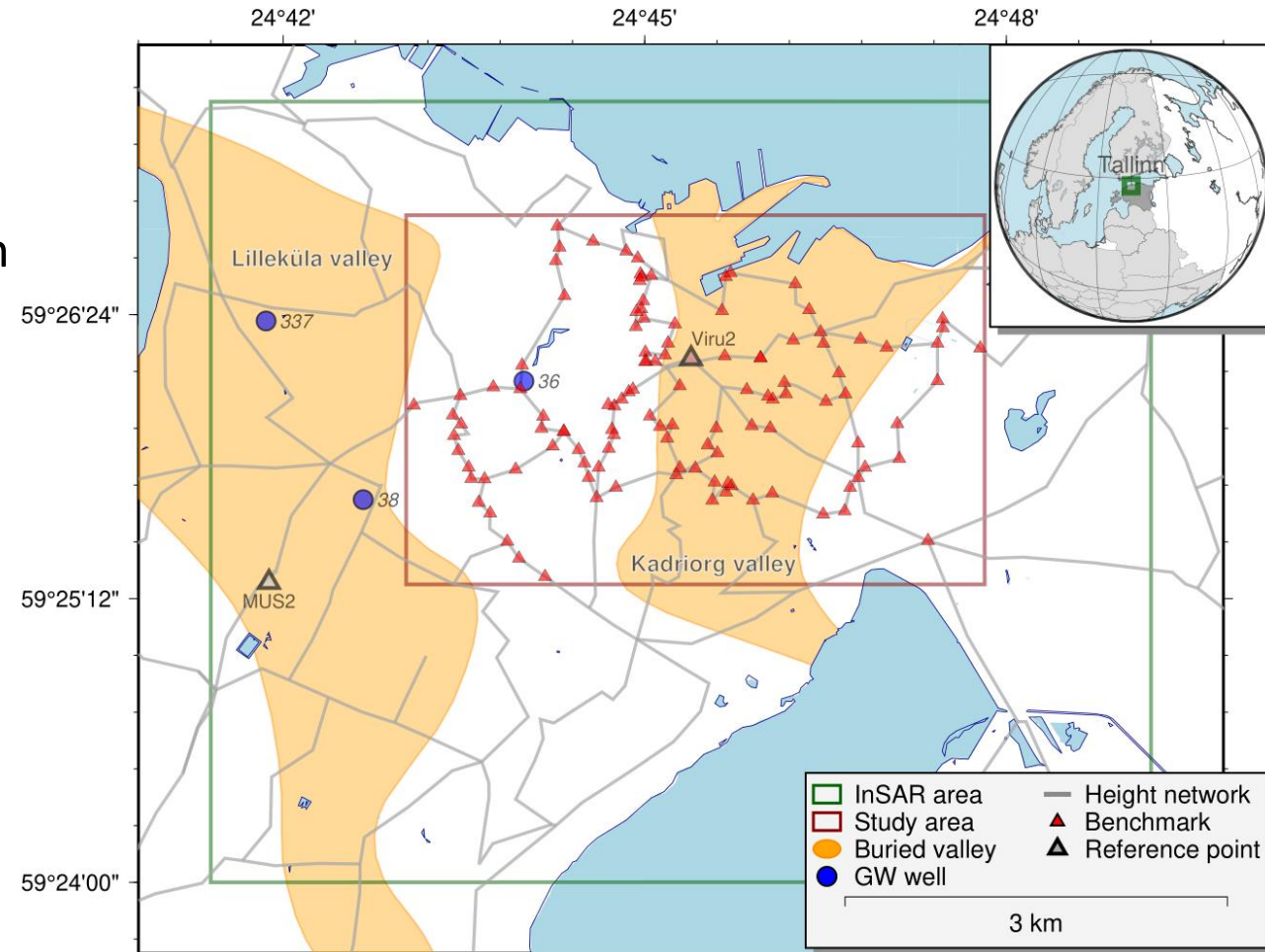
- The aim of InSAR analysis was to monitor the stability of benchmarks (BMs) in Tallinn city center

- Repeated levellings of 116 BMs

- Uncertainty of heights: $u(H_{lev}) = 0.23-0.31$ mm
- Uncertainty of velocities: $u(v_{lev}) = 0.03$ mm/y

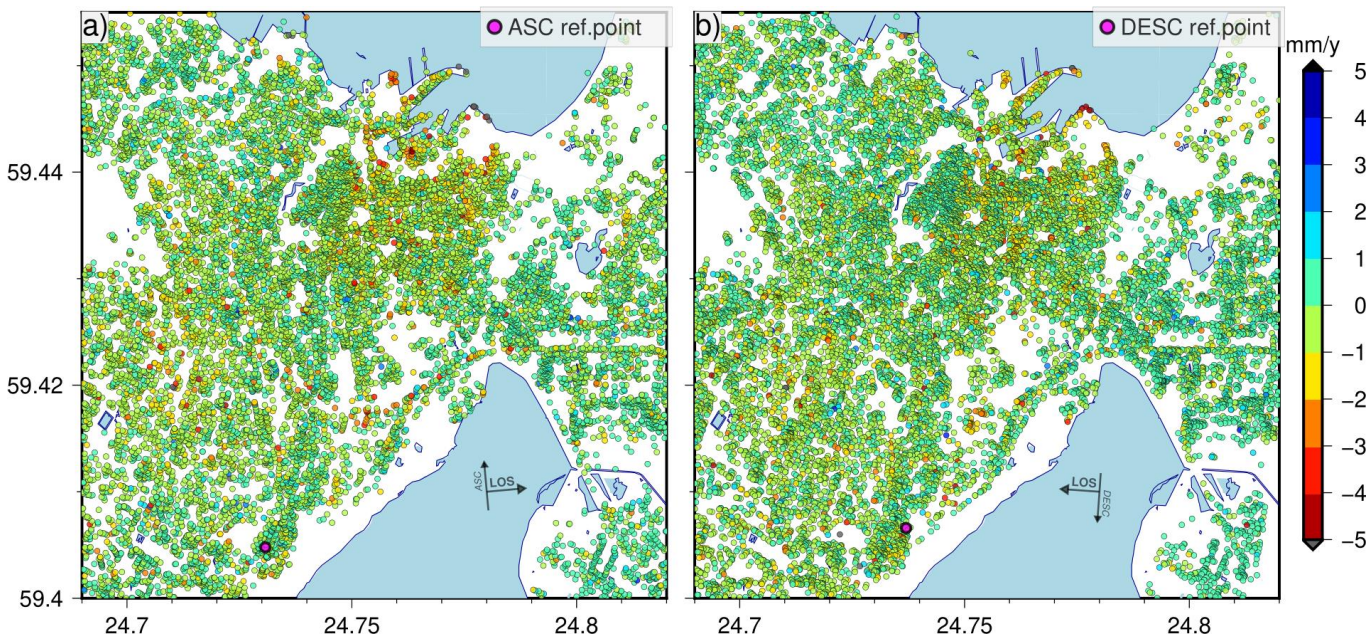


Precise leveling campaigns of the Tallinn height network undertaken in 2007/2008 and 2019

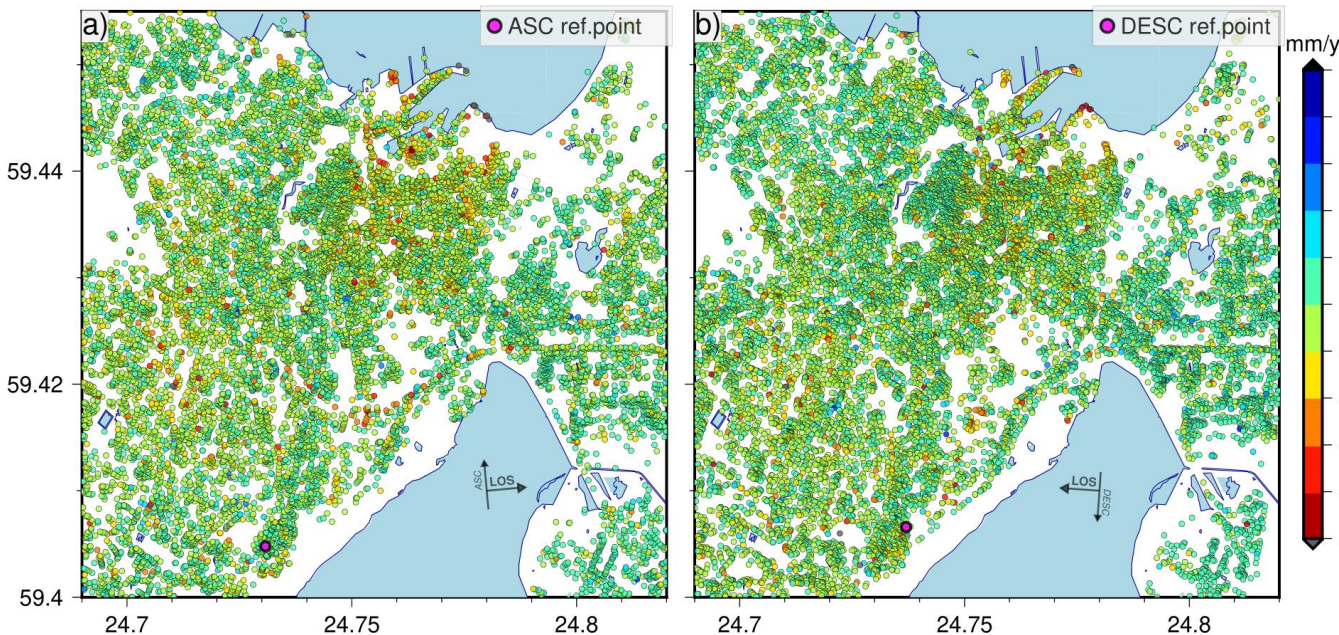


- Sentinel-1 data + persistent scatterer interferometry (PSI)
 - Line-of-sight (LOS) velocities from ASC, DESC orbits
 - Time frame: Jun 2016 – Nov 2021 (5.4 y)
 - Velocity solutions with about 250 and 50 images for long- and short-term periods (~1 yr)
 - Filtering: ASI+sCoh. > 1.4, tCoh. > 0.7

- Sentinel-1 data + persistent scatterer interferometry (PSI)
 - Line-of-sight (LOS) velocities from ASC, DESC orbits
 - Time frame: Jun 2016 – Nov 2021 (5.4 y)
 - Velocity solutions with about 250 and 50 images for long- and short-term periods (~1 yr)
 - Filtering: ASI+sCoh. > 1.4, tCoh. > 0.7



- Sentinel-1 data + persistent scatterer interferometry (PSI)
 - Line-of-sight (LOS) velocities from ASC, DESC orbits
 - Time frame: Jun 2016 – Nov 2021 (5.4 y)
 - Velocity solutions with about 250 and 50 images for long- and short-term periods (~1 yr)
 - Filtering: ASI+sCoh. > 1.4, tCoh. > 0.7



RESULTS:

LOS velocities of PS points in 2016.06 - 2021.11:

- ASC: 14452 p,
MEAN VEL = -0.3 (min -12.7, max 3.7) mm/y
- DSC: 16305 p,
MEAN VEL = -0.1 (min -11.2, max 4.3) mm/y
- Mean uncertainty ± 0.46 (min 0.42, max 0.87) mm/y

From linear regression: $\sigma_{\hat{\beta}_1}^2 = \frac{SSR}{(n-2) S_{xx}}$

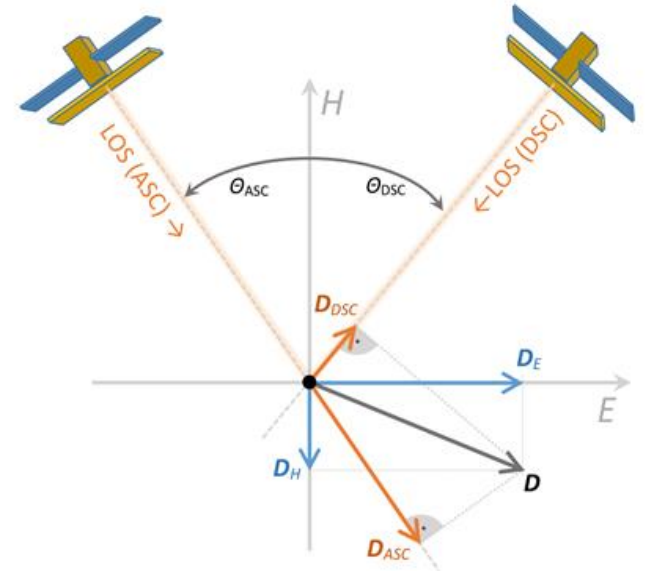
NB! Value about 5 times higher for short-term solutions

From LOS (1D) to E, H (2D)

- Decomposition of LOS (L) to east-west (E), vertical (H): $s_L = s_E \sin \theta \cos \varphi + \cancel{s_N \sin \theta \sin \varphi} + s_H \cos \theta$

- Solve linear system:

$$\begin{bmatrix} v_{L1} \\ v_{L2} \end{bmatrix} = \begin{bmatrix} \sin \theta_1 \cos \varphi_1 & \cos \theta_1 \\ \sin \theta_2 \cos \varphi_2 & \cos \theta_2 \end{bmatrix} \begin{bmatrix} v_E \\ v_H \end{bmatrix} = M \begin{bmatrix} v_E \\ v_H \end{bmatrix} \implies \begin{bmatrix} v_E \\ v_H \end{bmatrix} = M^{-1} \begin{bmatrix} v_{L1} \\ v_{L2} \end{bmatrix}$$



From LOS (1D) to E, H (2D)

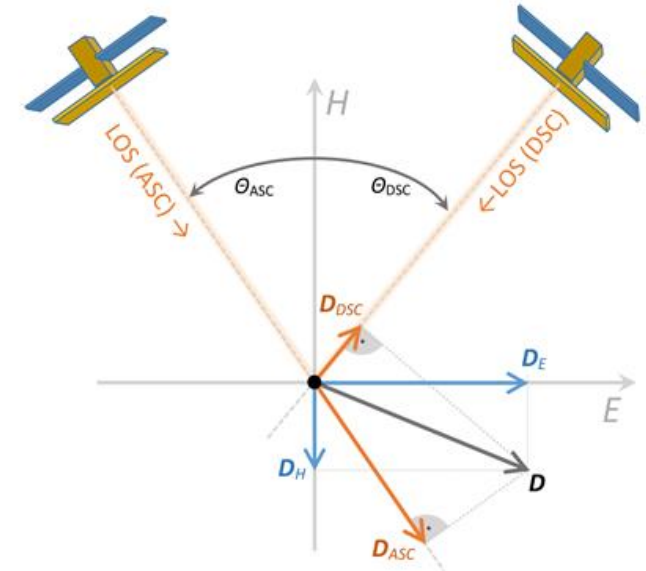
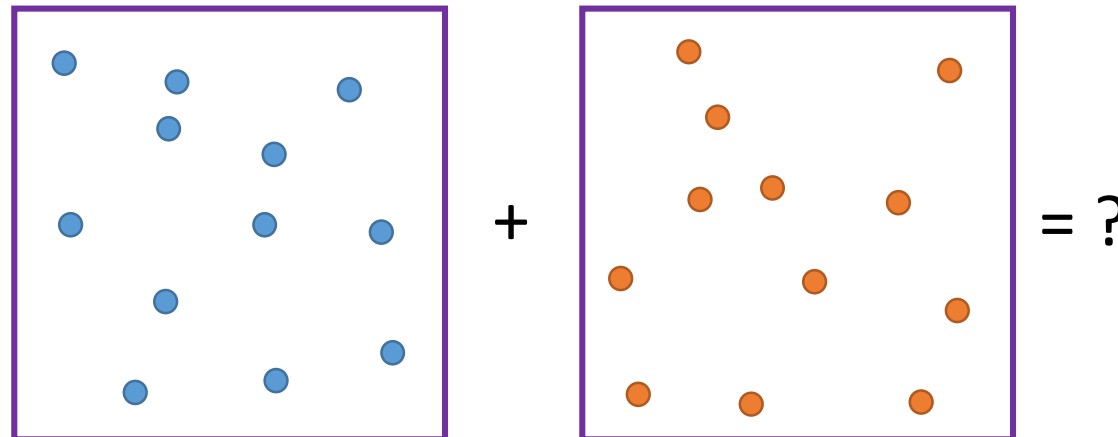
- Decomposition of LOS (L) to east-west (E), vertical (H): $s_L = s_E \sin \theta \cos \varphi + \cancel{s_N \sin \theta \sin \varphi} + s_H \cos \theta$

- Solve linear system:

$$\begin{bmatrix} v_{L1} \\ v_{L2} \end{bmatrix} = \begin{bmatrix} \sin \theta_1 \cos \varphi_1 & \cos \theta_1 \\ \sin \theta_2 \cos \varphi_2 & \cos \theta_2 \end{bmatrix} \begin{bmatrix} v_E \\ v_H \end{bmatrix} = M \begin{bmatrix} v_E \\ v_H \end{bmatrix} \implies \begin{bmatrix} v_E \\ v_H \end{bmatrix} = M^{-1} \begin{bmatrix} v_{L1} \\ v_{L2} \end{bmatrix}$$

- How to combine different orbits?

- L1 (ASC), L2 (DESC) points do not overlap spatially



From LOS (1D) to E, H (2D)

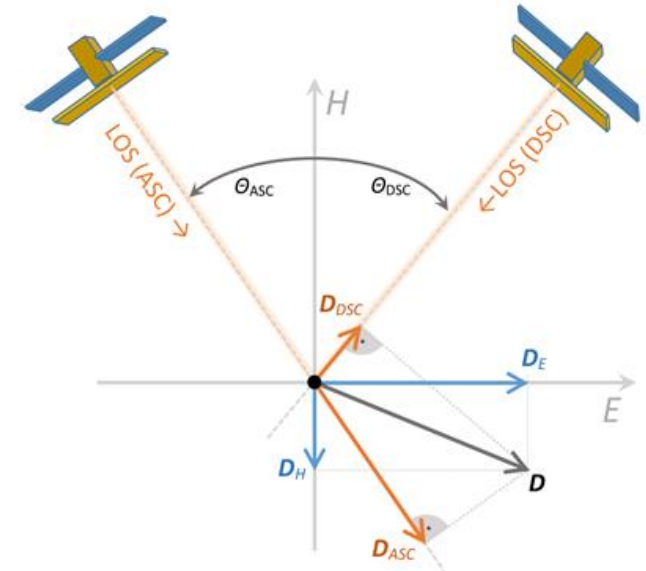
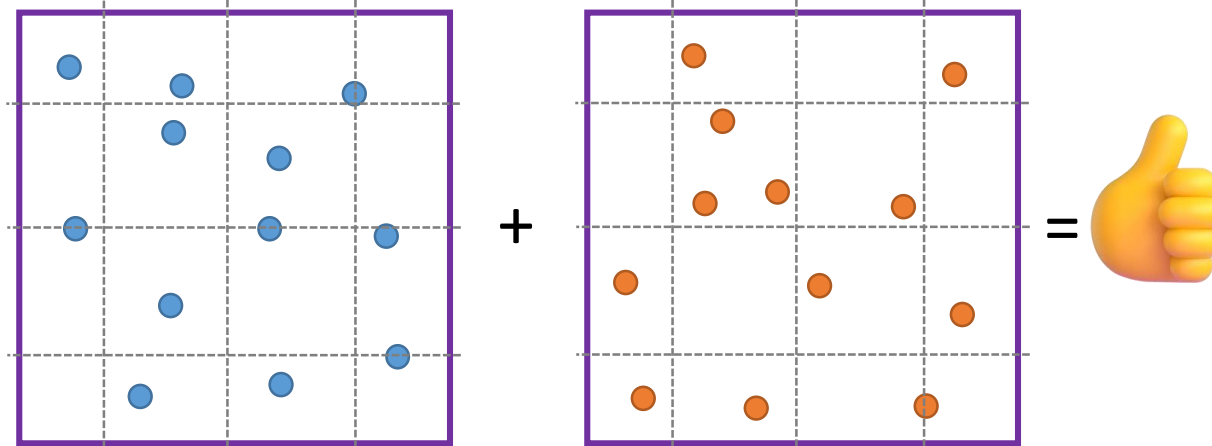
- Decomposition of LOS (L) to east-west (E), vertical (H): $s_L = s_E \sin \theta \cos \varphi + \cancel{s_N \sin \theta \sin \varphi} + s_H \cos \theta$

- Solve linear system:

$$\begin{bmatrix} v_{L1} \\ v_{L2} \end{bmatrix} = \begin{bmatrix} \sin \theta_1 \cos \varphi_1 & \cos \theta_1 \\ \sin \theta_2 \cos \varphi_2 & \cos \theta_2 \end{bmatrix} \begin{bmatrix} v_E \\ v_H \end{bmatrix} = M \begin{bmatrix} v_E \\ v_H \end{bmatrix} \implies \begin{bmatrix} v_E \\ v_H \end{bmatrix} = M^{-1} \begin{bmatrix} v_{L1} \\ v_{L2} \end{bmatrix}$$

- How to combine different orbits?

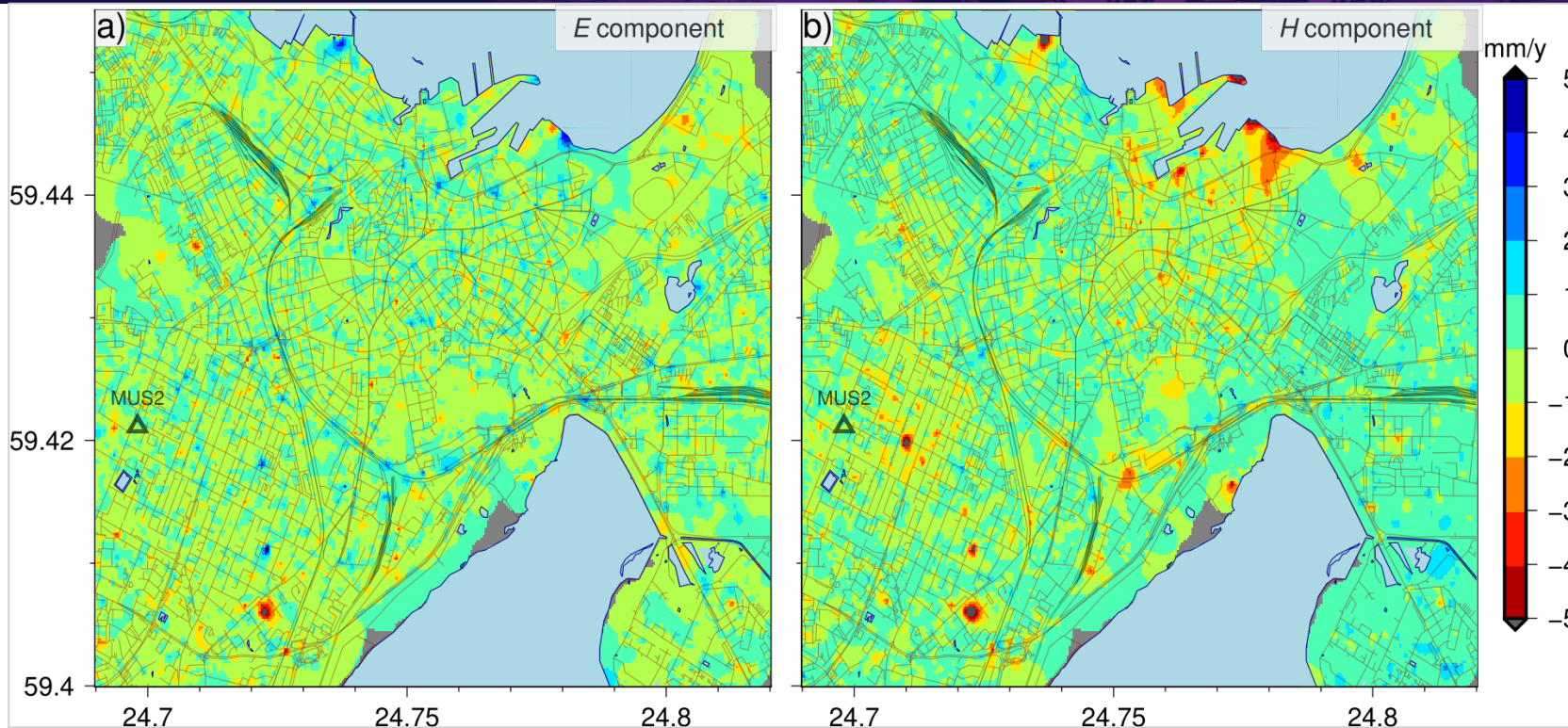
- $L1$ (ASC), $L2$ (DESC) points do not overlap spatially
- Gridding



GMT - The Generic Mapping Tools, an open source software, <https://www.generic-mapping-tools.org/>

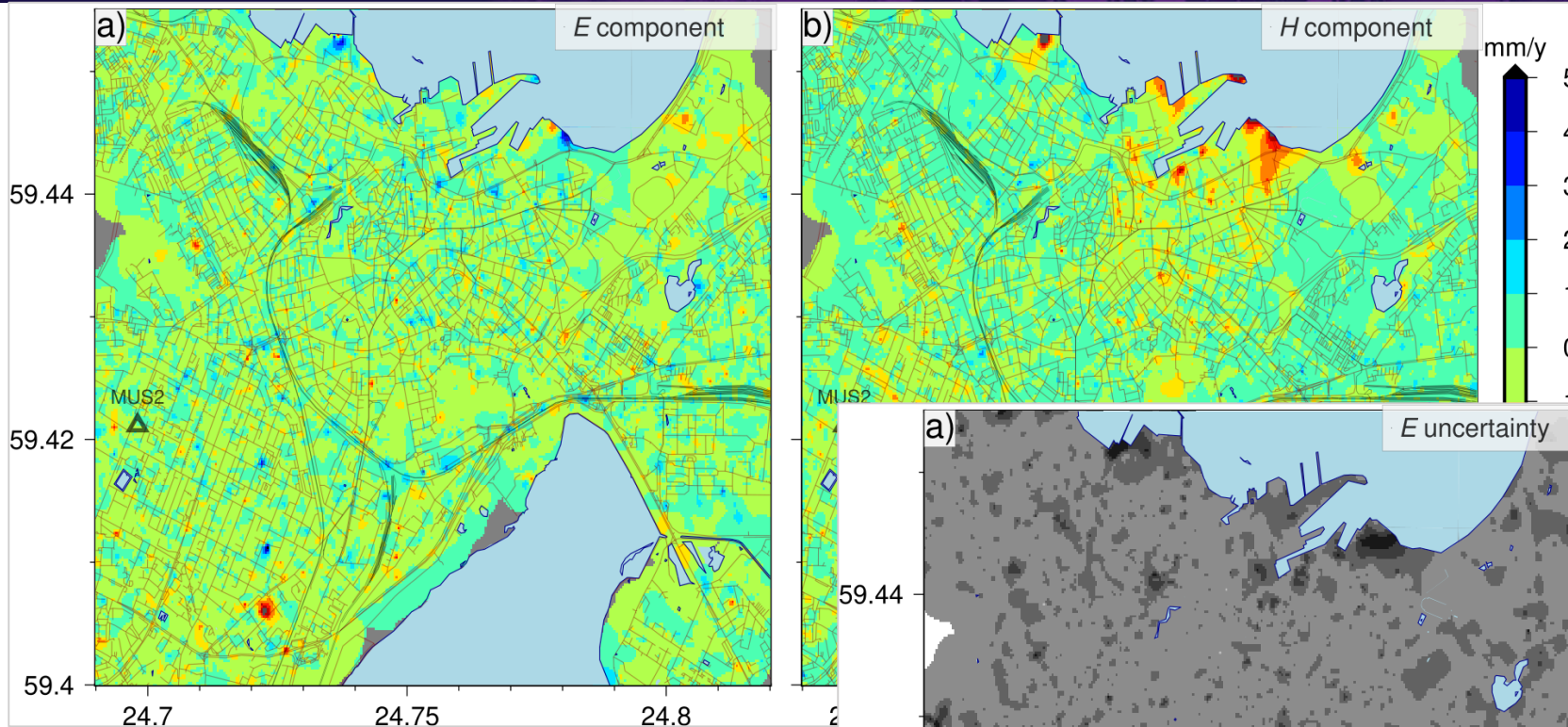
- Gridding of LOS velocity models with GMT
 - `blockmean`: $d\text{Lon}/d\text{Lat} = 1.44''/0.72'' = 0.0004^\circ/0.0002^\circ$ (~23/22 m)
 - `surface` (2D splines, T=0.3)
 - grid nodes with a distance more than 300 m from the nearest PS points were set to NaN
- E, H models with `grdmath`: $[v_E \ v_H]^T = M^{-1} [v_{\text{LOS1}} \ v_{\text{LOS2}}]$
- Variance grids: $[D(v_E) \ D(v_H)]^T = M^{-1} [D(v_{\text{LOS1}}) \ D(v_{\text{LOS2}})]^T (M^{-1})^T$
- Reference for E, H models: $v_{2D} = 0.0$ mm/y at pGNSS “MUS2”
 - VEL (2012.3 – 2021.9, dT = 9.6 a) in IGS14 (from <http://geodesy.unr.edu/NGLStationPages/stations/MUS2.sta>):
 $v_E = -0.17 \pm 0.19$ mm/y and $v_H = 3.14 \pm 0.79$ mm/y

Long term solution

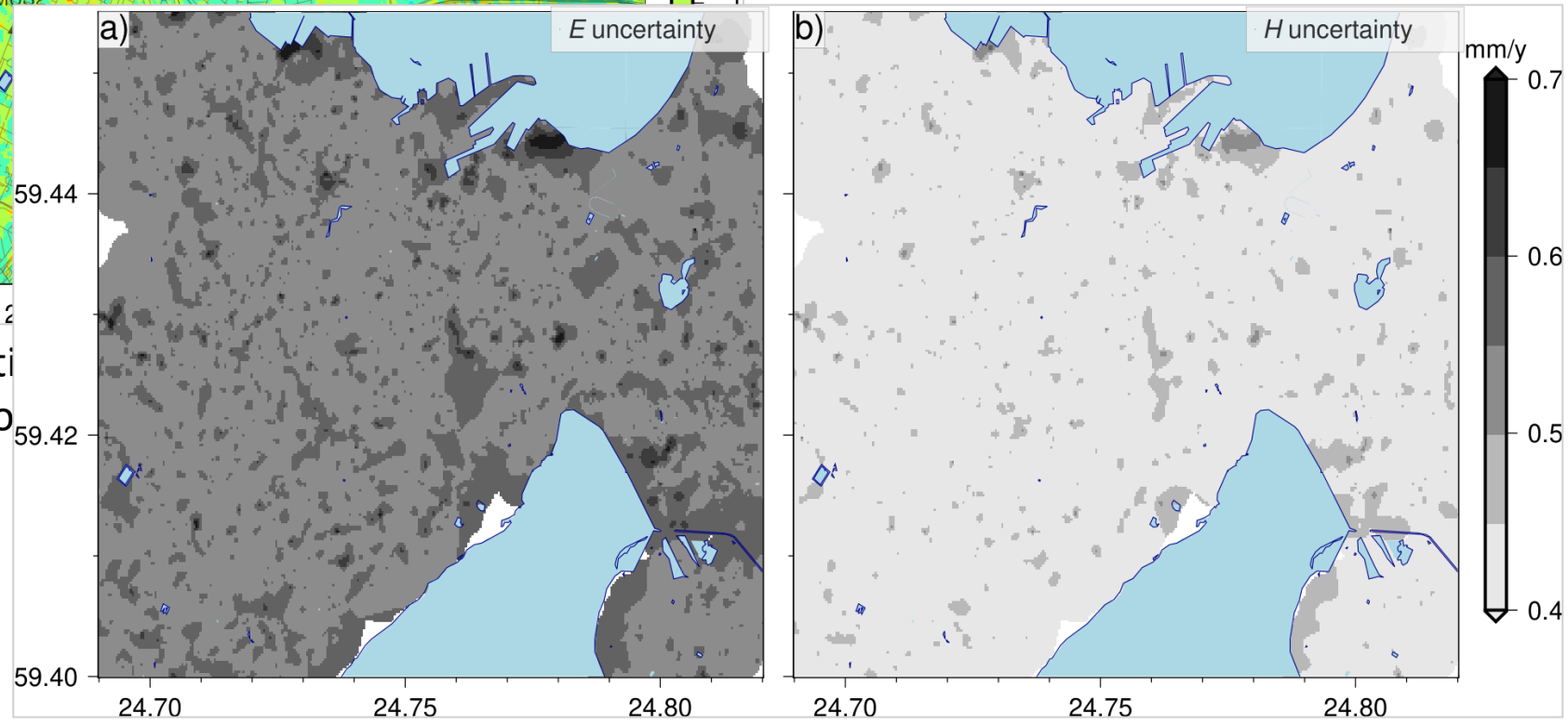


Velocity solutions for east-west (E) and vertical (H) components (2016-2021) decomposed from the LOS velocities. The solutions have been fixed at the location of “MUS2” permanent GNSS station

Long term E, H solutions

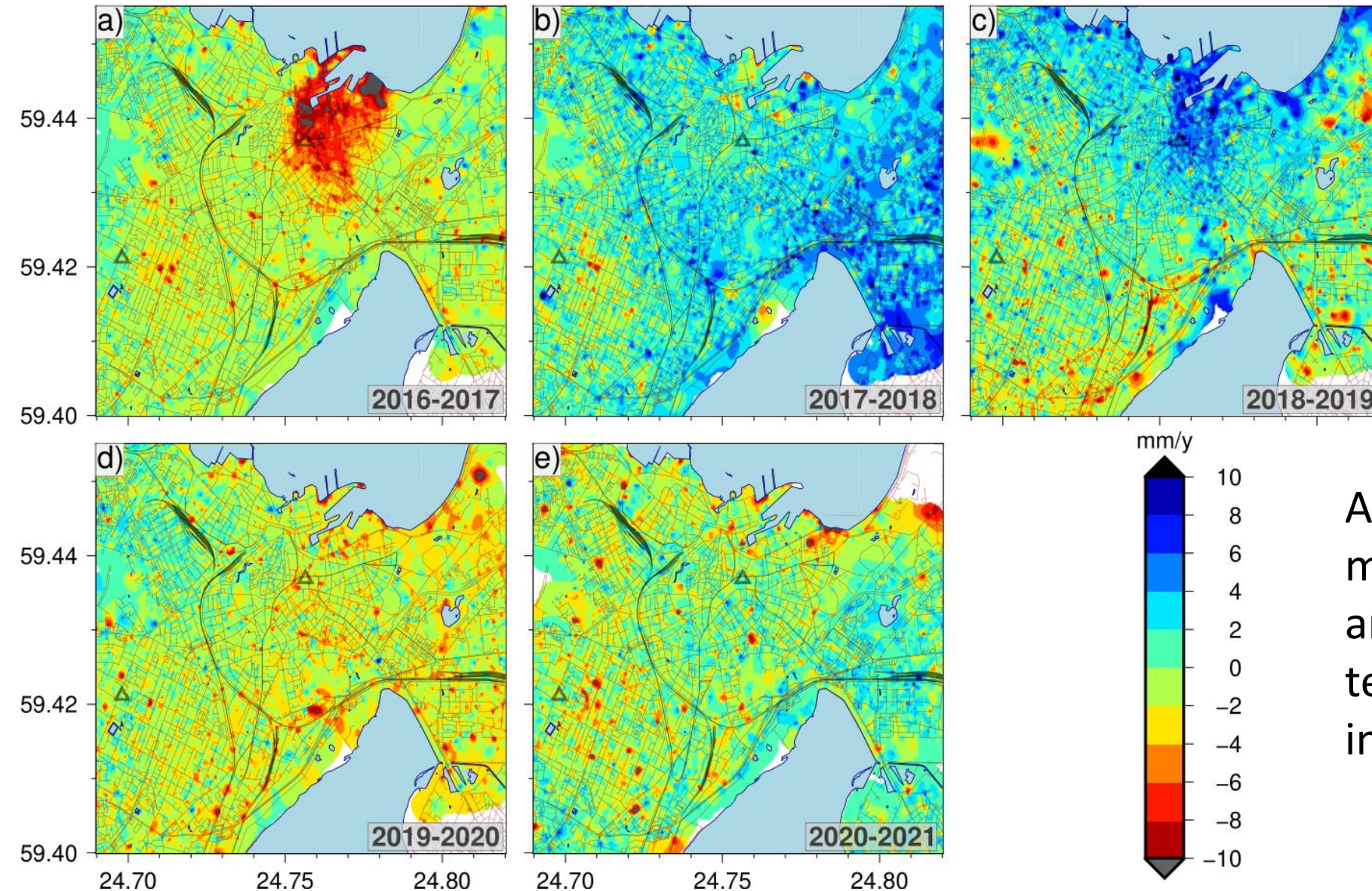


Uncertainty grids of E, H velocity solutions (2016-2021)



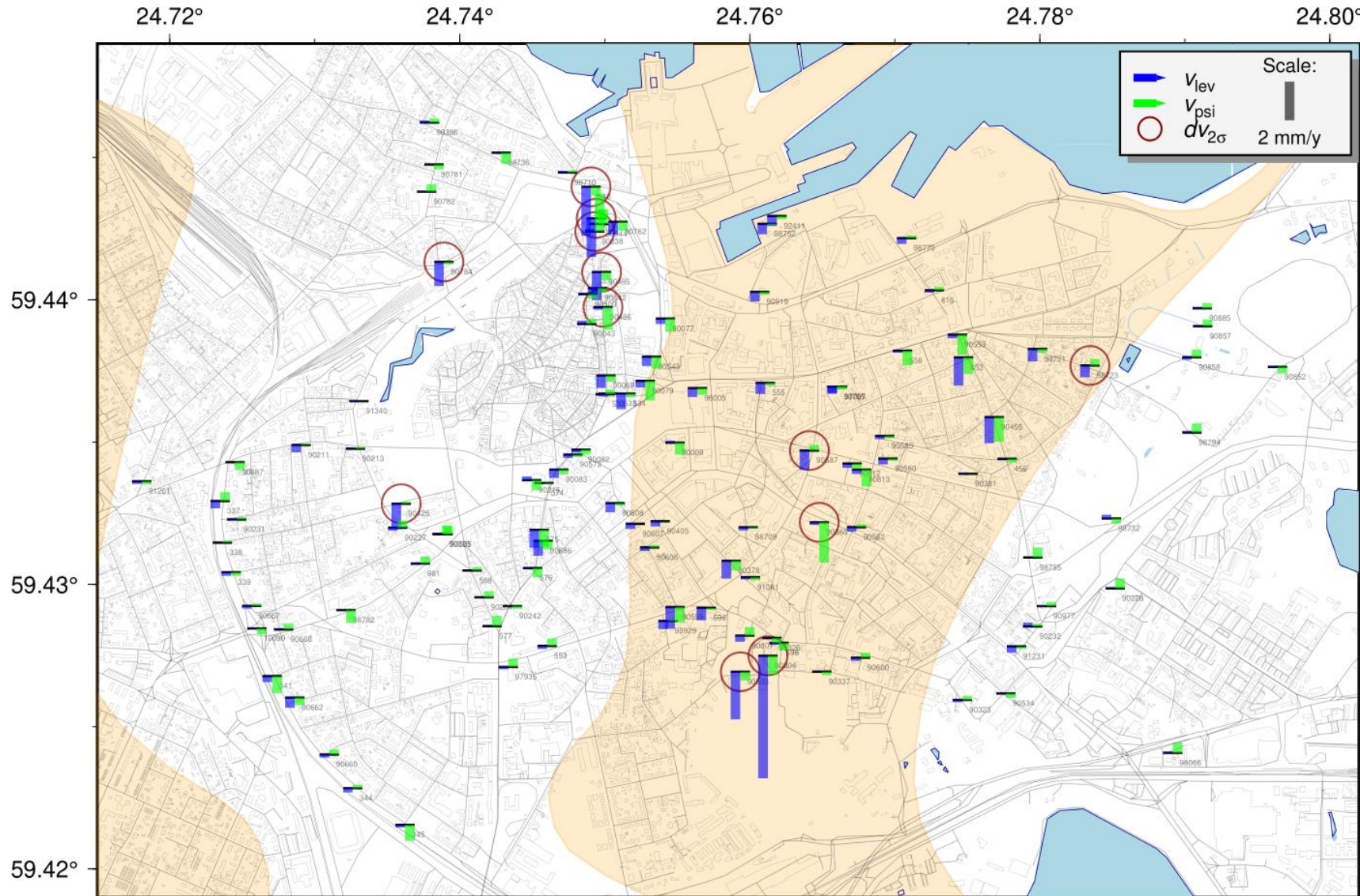
Velocity solutions for east-west (E) and vertical (H) components, decomposed from the LOS velocities. The location of the permanent GNSS station "MUS2" is marked with a triangle on the left side of the maps.

Short term H solutions



A series of vertical velocity models from yearly InSAR analyses to monitor short-term deformation changes in Tallinn city center

Comparison 1



The comparison of the leveled (2007-2019) and InSAR velocities (2016-2021) at 116 BMs of the Tallinn height network

Testing statistical significance of differences $dv = v_{lev} - v_{psi}$ between leveled and InSAR velocities:

○ – significant dv at 12 BMs (10%)

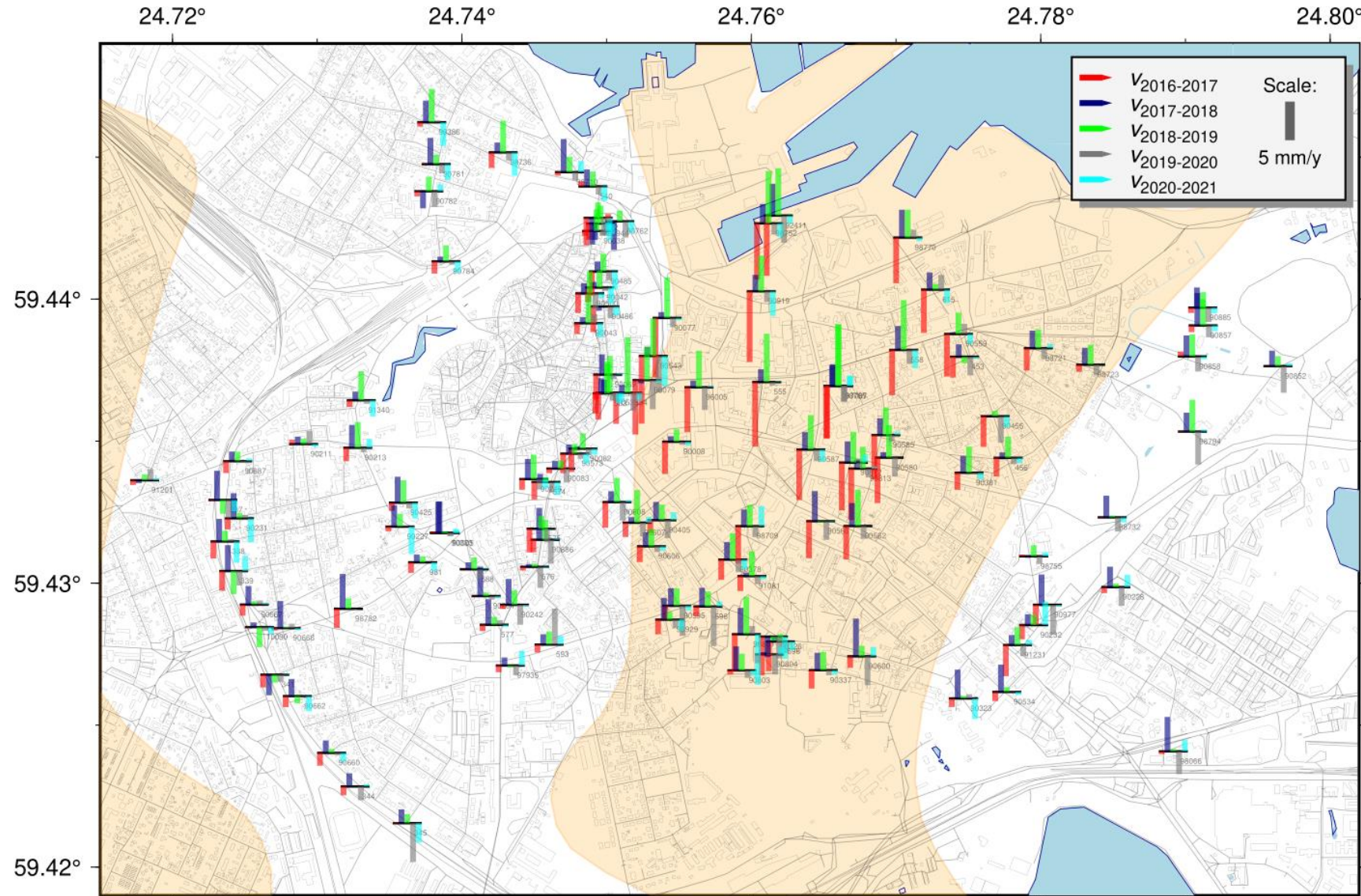
Mean uncertainty (2σ):

$$u(v_{lev}) = 0.06 \text{ mm/y}$$

$$u(v_{psi}) = 0.84 \text{ mm/y}$$

$$u(dv) = \pm 0.84 \text{ mm/y}$$

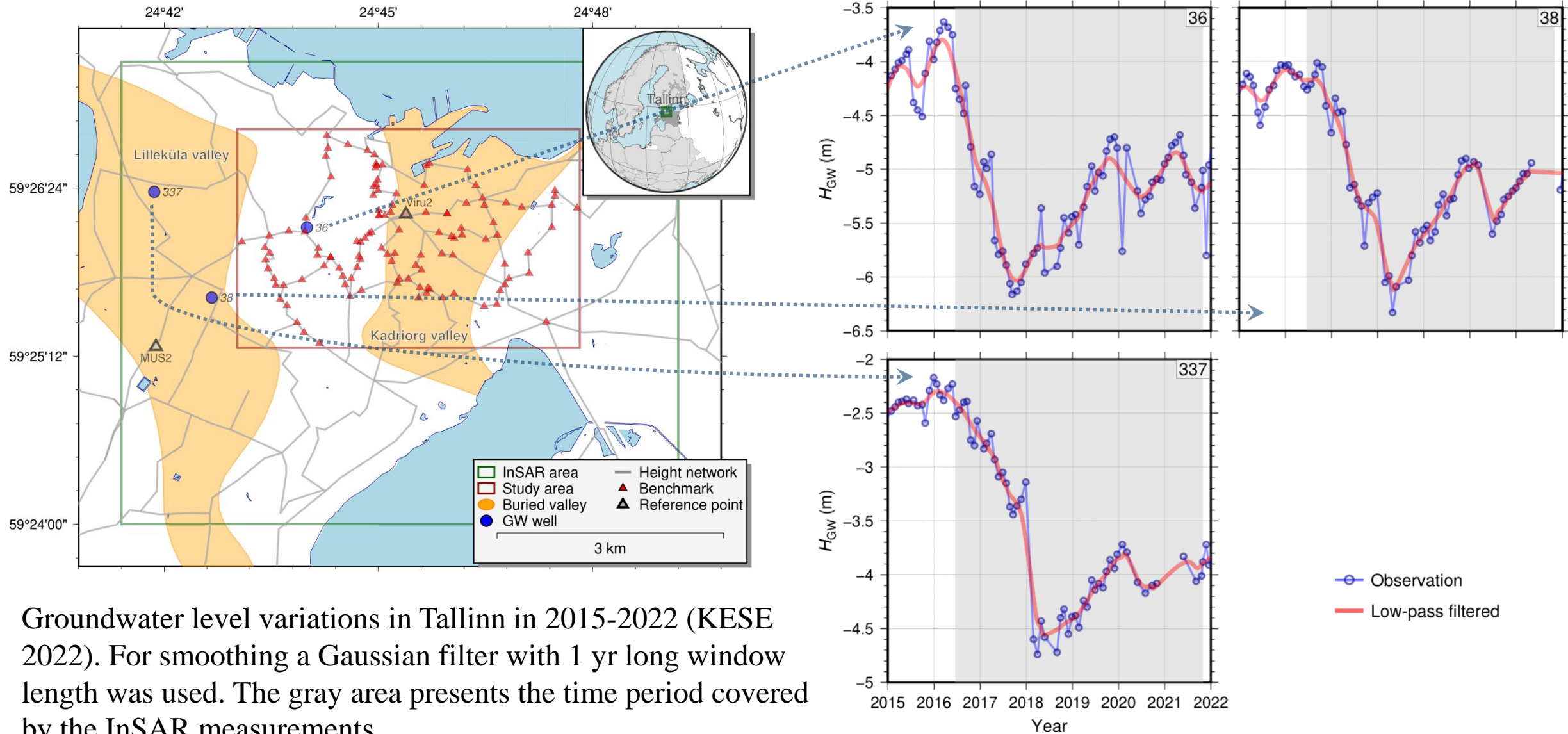
Comparison 2



Velocities from yearly InSAR solutions at the benchmarks of Tallinn height network

- Important to understand these findings to evaluate InSAR results
- Historical studies based on repeated leveling:
 - Maps of vertical land movement (VLM) compiled by Zhelnin (1958), Lutsar (1965), Vallner and Lutsar (1966), Kall and Torim (2003)
 - The sinking of the Tallinn city center was noticed in 1951
 - In 1960s, the highest subsidence rates up to 30 mm/year were observed
 - From 1964 onwards, the sinking rate decreasing, the leveling repeated within 1986-2000 showed that sinking stopped or reversed into rising
 - A correlation has been found between the leveling results, the geological structure and **groundwater level changes**
 - Largest VLM rates over **the ancient valleys buried under quaternary sediments**

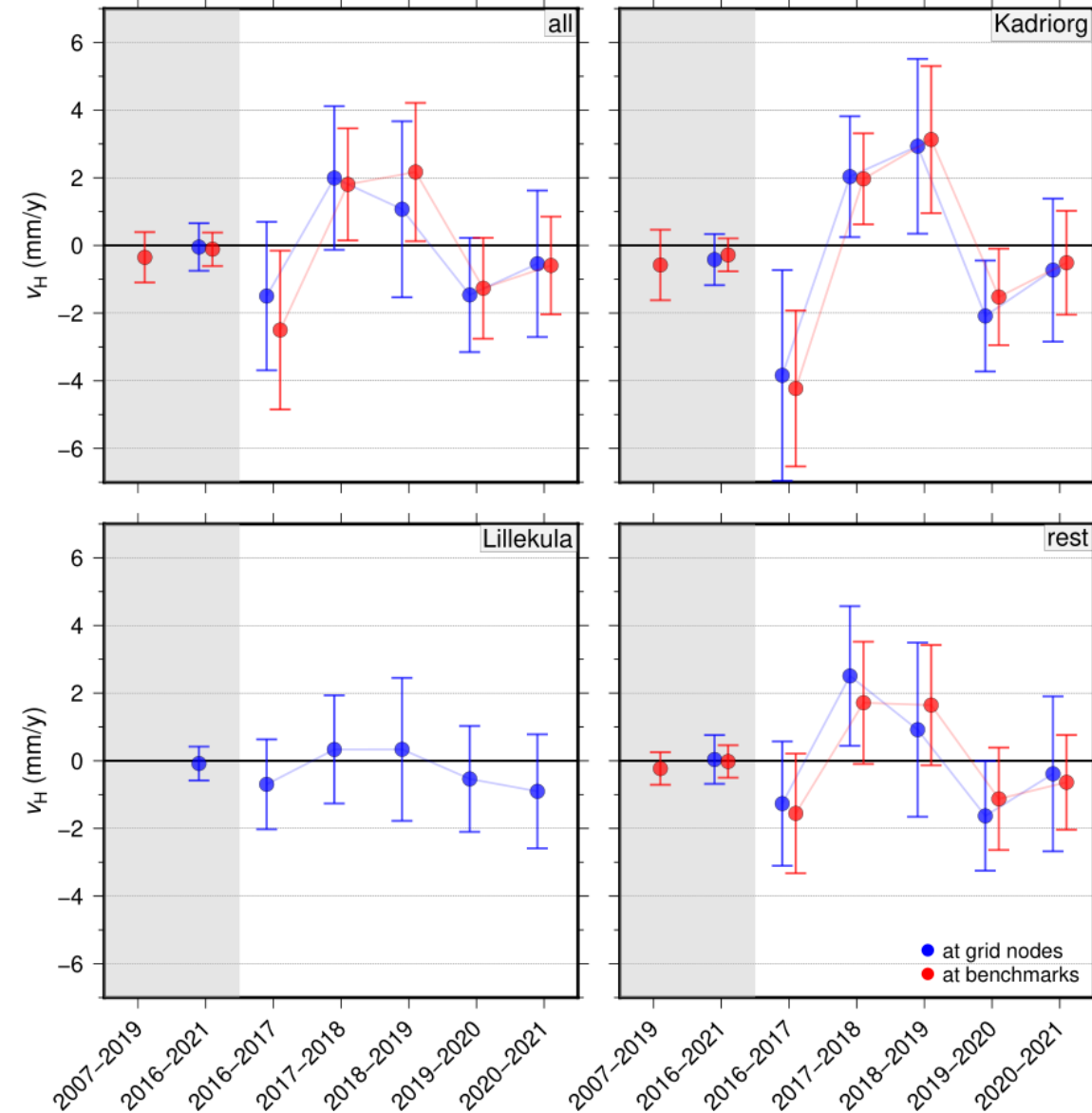
Groundwater level in Tallinn



Groundwater level variations in Tallinn in 2015-2022 (KESE 2022). For smoothing a Gaussian filter with 1 yr long window length was used. The gray area presents the time period covered by the InSAR measurements.

Statistics over different areas

- Mean value with standard deviation (represented by error bars) was estimated over
 - The nodes of InSAR vertical velocity grids (blue)
 - The leveled and InSAR derived velocities at the benchmarks (red)
- The gray background separates long-term solutions (leveling, InSAR) from yearly solutions (InSAR)
- The statistics were estimated for all study area (all), Kadriorg and Lilleküla buried valleys, and the rest (valleys excluded)



Conclusions

- InSAR is suitable to monitor the stability (and accuracy) of geodetic infrastructure
 - Long-term InSAR results were consistent with repeated leveling
 - Differences not significant at 104 BMs (90%)

- InSAR is suitable to monitor the stability (and accuracy) of geodetic infrastructure
 - Long-term InSAR results were consistent with repeated leveling
 - Differences not significant at 104 BMs (90%)
- Short-term InSAR analysis showed subsiding and uplifting city center of Tallinn
 - The effect of hydrogeological process: temporal coherence with groundwater level change, spatial coherence with buried valleys
 - Q: The effect on the city environment and infrastructure of Tallinn?

- InSAR is suitable to monitor the stability (and accuracy) of geodetic infrastructure
 - Long-term InSAR results were consistent with repeated leveling
 - Differences not significant at 104 BMs (90%)
- Short-term InSAR analysis showed subsiding and uplifting city center of Tallinn
 - The effect of hydrogeological process: temporal coherence with groundwater level change, spatial coherence with buried valleys
 - Q: The effect on the city environment and infrastructure of Tallinn?
- A: New InSAR analysis complemented with terrestrial geodetic measurements, rigorous hydrogeological modeling and additional geological, hydrological data would be a useful tool to model processes and predict the land motion in Tallinn
- Paper submitted:
 - Oja, T., and Gruno, A. (2022) Monitoring of millimeter-scale deformations in Tallinn using repeated leveling and PS-InSAR analysis of Sentinel-1 data. *Advances in Geodesy and Geoinformation*

Thank you for your attention!
Questions?

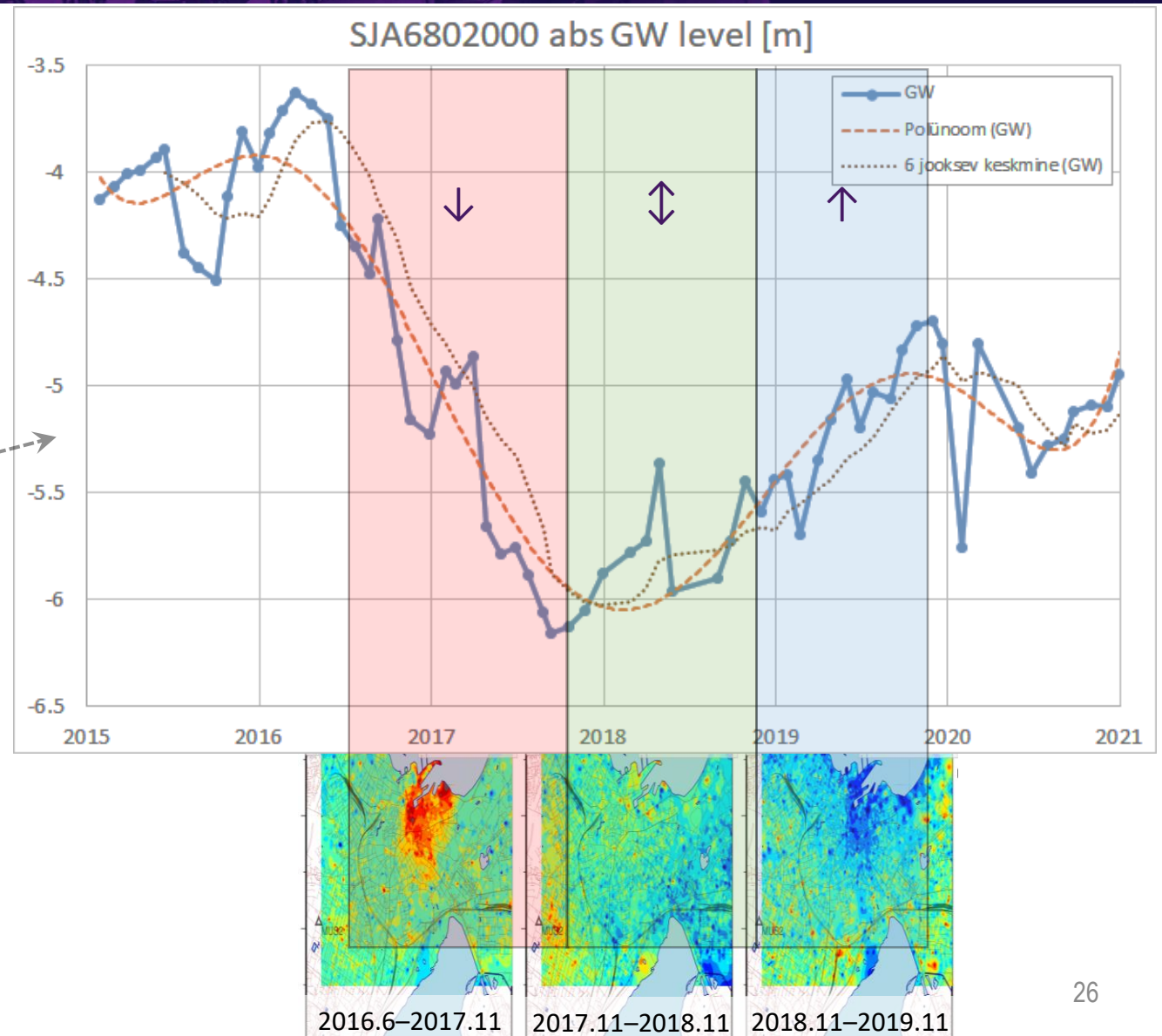
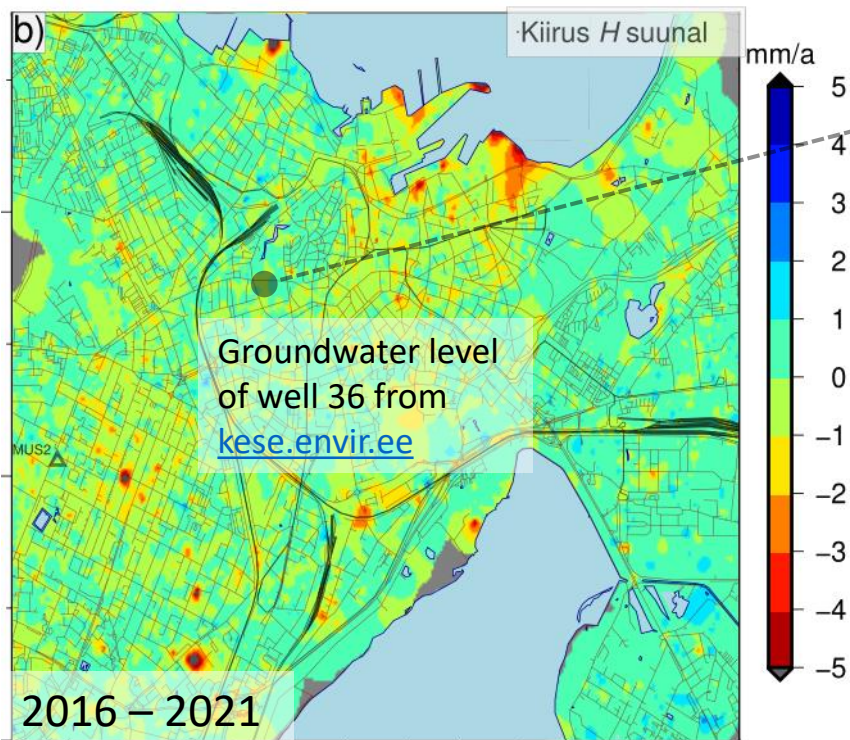
Tonis.Oja@datel.ee
Anti.Gruno@datel.ee



Groundwater level in Tallinn (2)

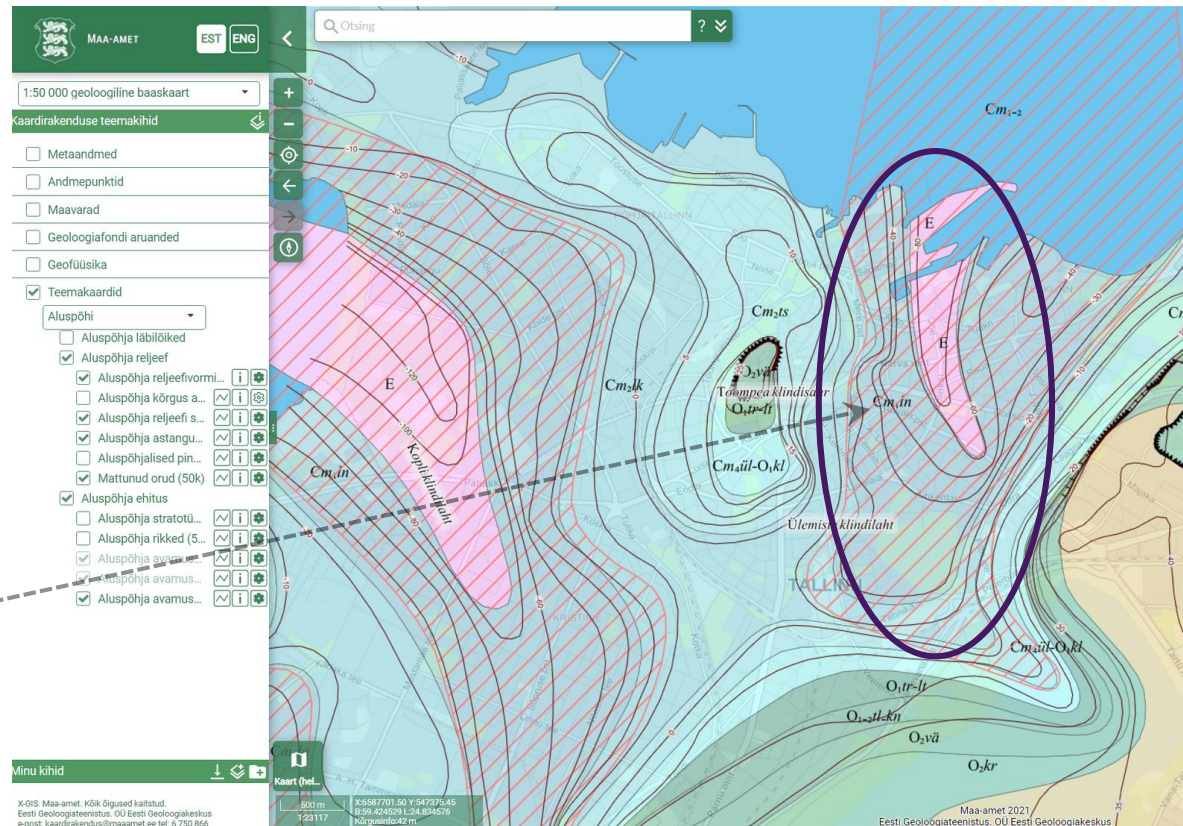
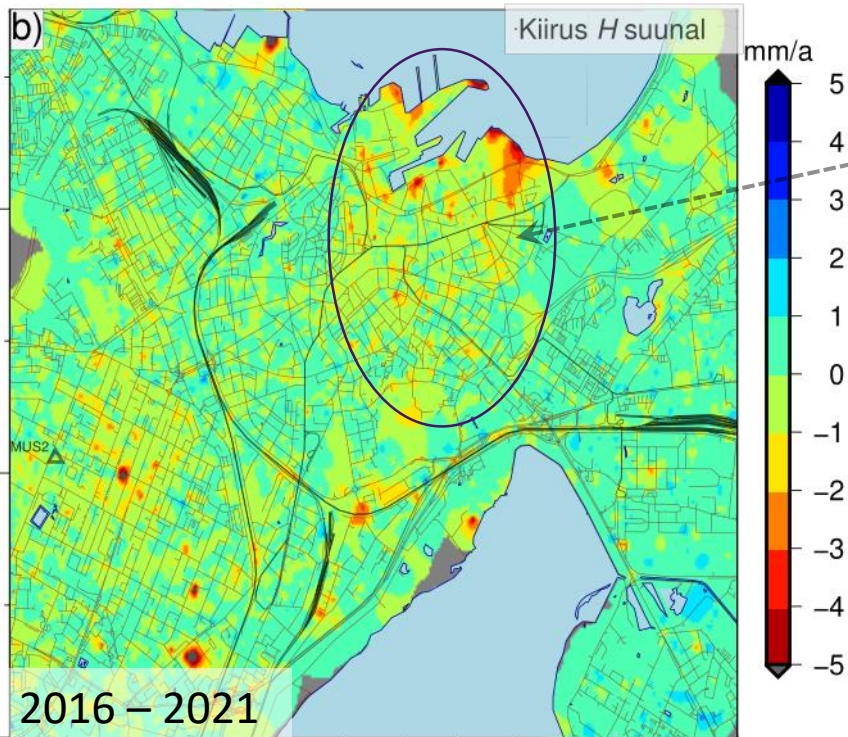
- Possible sources

- Geology (buried valleys, bedrock escarpments)
- Hydrology (groundwater level variations)



Buried valleys in Tallinn

- Possible sources
 - Geology (buried valleys, bedrock escarpments)



Geological base map 1:50000
Estonian Land Board 2021
geoportaal.maaamet.ee